Image Sequence Understanding through Narrative Sensemaking



Introduction

Conversational AI systems would benefit from a method of understanding and discussing image sequences as humans do.

- Humans make sense of what is happening in images beyond the directly observable.
- It is natural for humans to organize their understanding using narrative.¹



Figure 1 – A sequence of images with human-written explanations.²

We aim to create a system that can generate machine-usable knowledge graphs from image sequences using the human-inspired process of **sensemaking**.

Sensemaking

Sensemaking is the process of creating consistency between and coherence observations in an environment and a person's existing knowledge of the world.³

- Connections are an important part of tying together what one observes.⁴
- Aim to interconnect observations as much as possible using existing knowledge while remaining consistent (not selfalso contradictory).
- The types of connections people use can be found in human-made narratives, and categorized as: spatial, temporal, causal, referential, affective (emotion/motivation).⁵

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Image Sequence Understanding System

The image sequence understanding system takes observations about a sequence of images, performs a sensemaking process to hypothesize additional relationships between observations, then produces a **knowledge graph** combining its observations with its additional relationships.

Observations

- Visually observable facts about each image.
- Consist of scene graphs, with objects and their relationships as nodes and edges (Fig. 2).

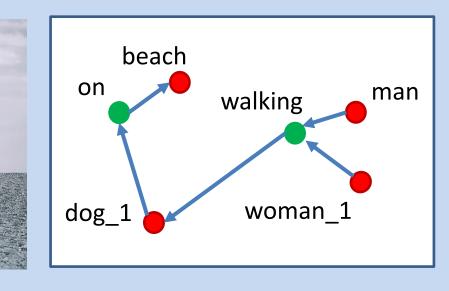
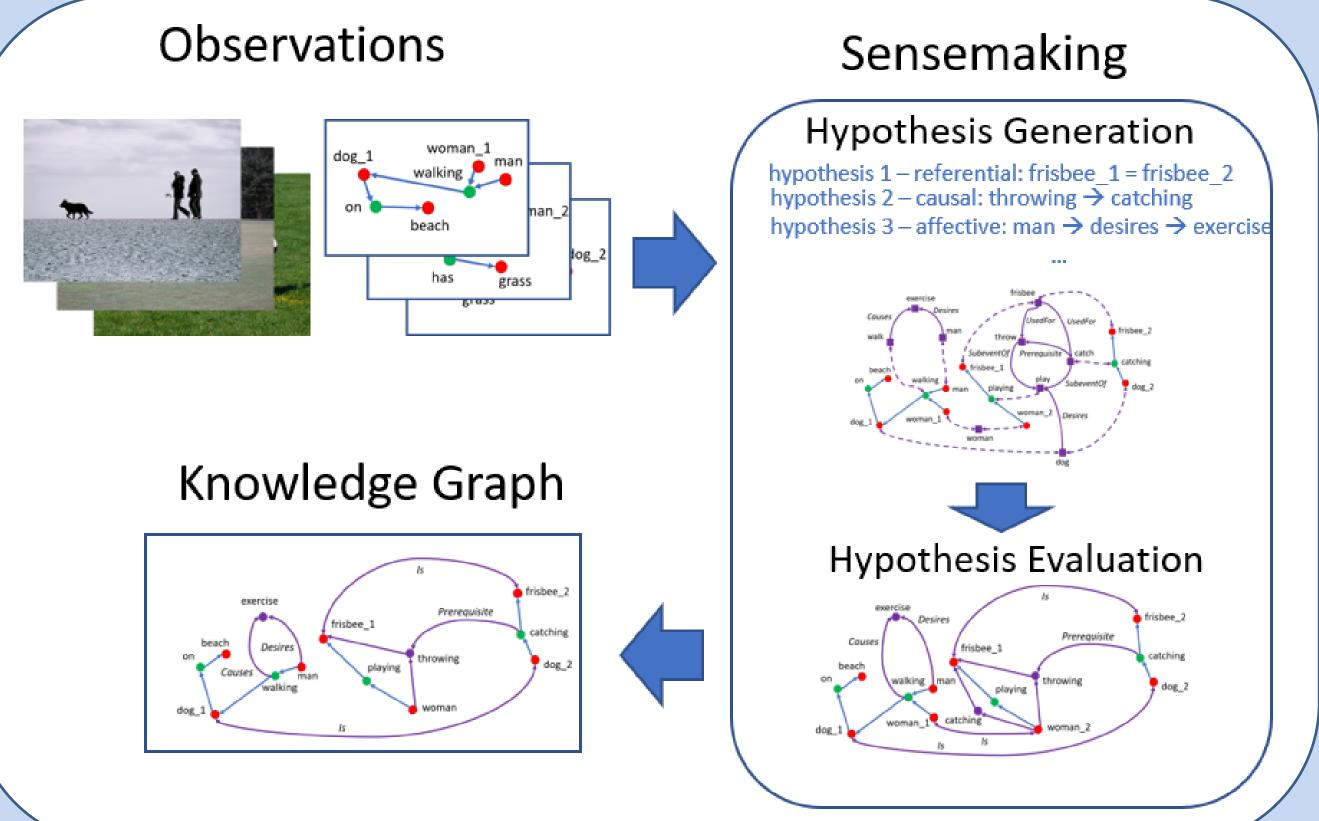
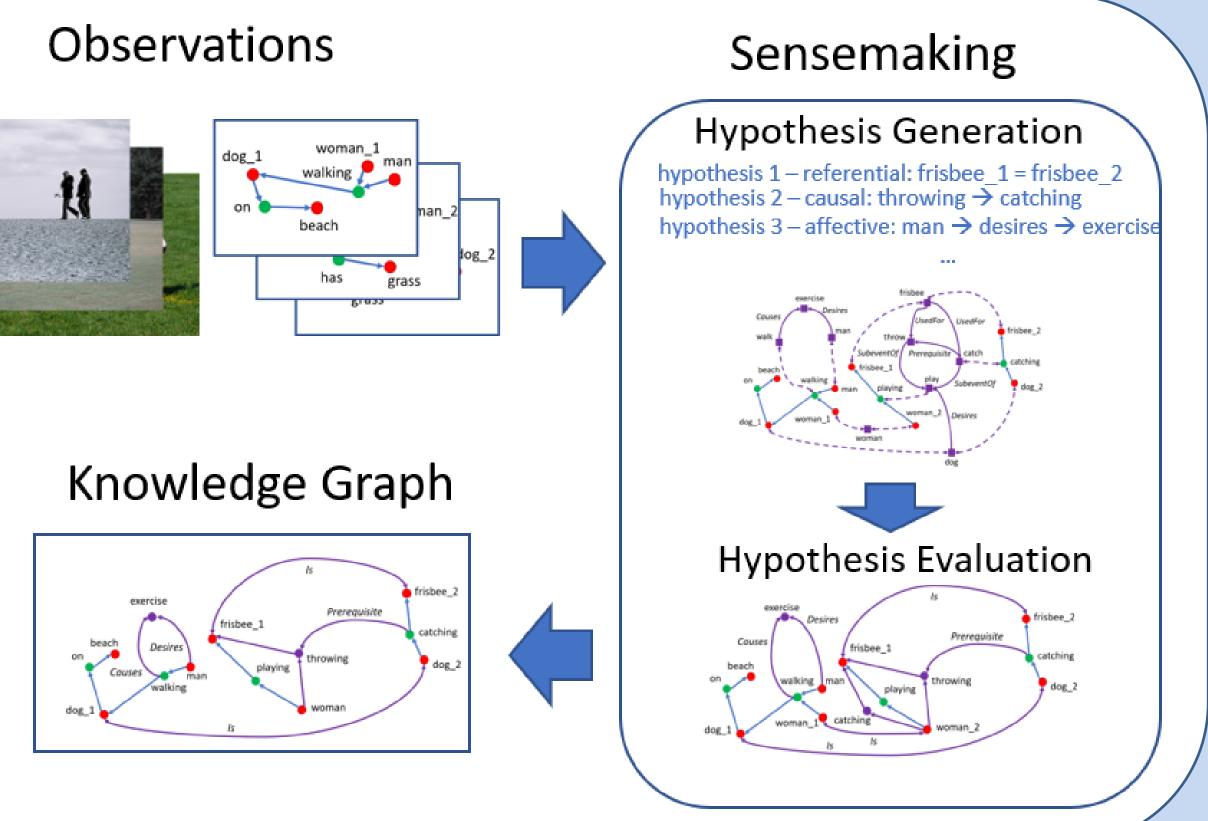


Figure 2 – Image with excerpt of its scene graph from the Visual Genome dataset.





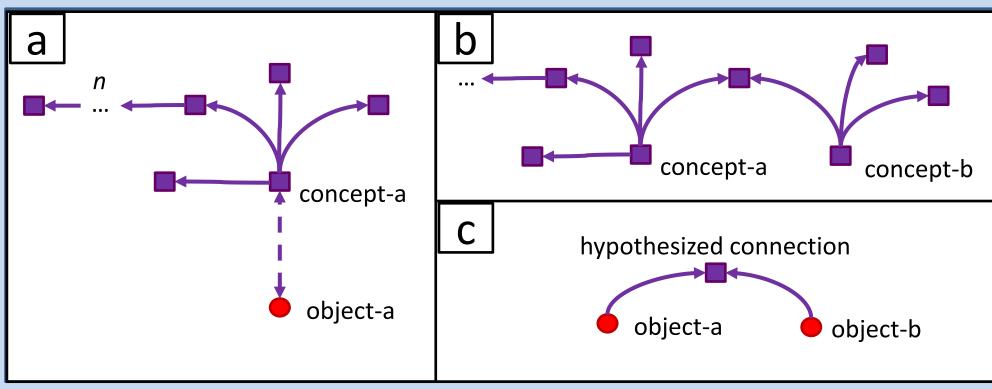
Sensemaking Subsystem

Subsystem to hypothesize additional relationships between observations in a two-step process of hypothesis generation and hypothesis evaluation.

Hypothesis Generation

- Over-generate possible additional relationships.
- ConceptNet common-sense knowledge network as existing knowledge, with generic concepts as nodes and relationships as edges.
- ConceptNet relations are selected and organized by system based on narrative connection types.
- Scene graph nodes are equated to their ConceptNet concept nodes (Fig. 4, a).

• Paths between concepts (Fig. 4, b) are taken as hypothesized additional relationships (Fig. 4, c).



• Aim to connect as much of the knowledge graph as possible while maintaining consistency. • Choose which hypothesized additional relationships to keep as a Multi-Objective Optimization Problem:

Find set of hypothesis, h_m , that maximizes score of each objective function, $f_i(x)$, where each hypothesis set is part of the set of feasible hypothesis sets, H_f .

Connectivity and Density, measures of graph interconnectedness. *Support,* scorable evidence from scene graph confidence values and ConceptNet edge weights. A hypothesis set is *feasible* if its elements do not contradict each other, decided by heuristic-based checks per narrative relationship type.

Figure 4 – Process of generating single hypothesis.



Hypothesis Evaluation

$$max_1^m(f_i(x))|h_j \in H_f$$

Three objective functions are used:

System utilizes two external data sources: Visual Genome Dataset acts as a source of human-annotated scene graphs used for the system's observations.

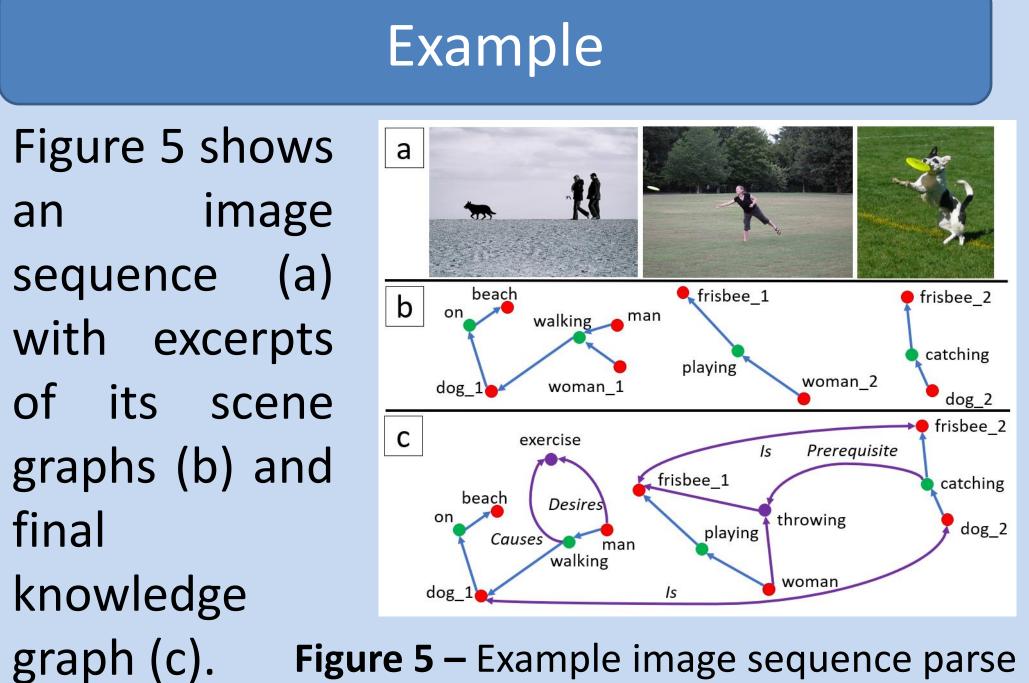
• Images with ROI bounding boxes paired with object and relationship annotations. Automated scene graph generation

methods do also exist (e.g. Graph-RCNN). **ConceptNet** acts as system's commonsense

knowledge source. Crowd-sourced knowledge network of generic concepts and their relationships. Uses a known finite set of relationships mappable to narrative relationships.

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Data Sources



Future Work

• Implement architecture into full system. • Investigate whether system's hypothesized information is of value to human readers.

References

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