

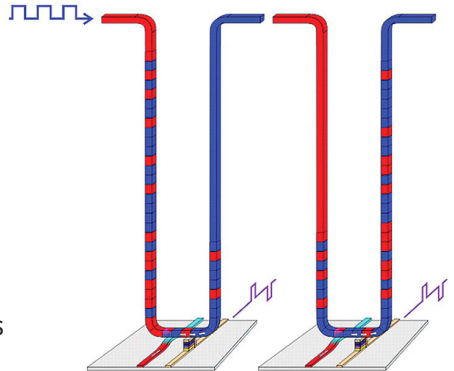
Micromagnetics and Skyrmions

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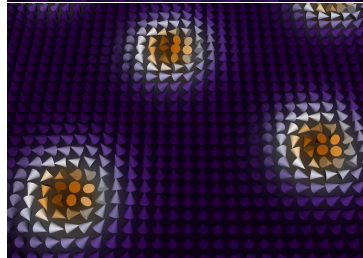
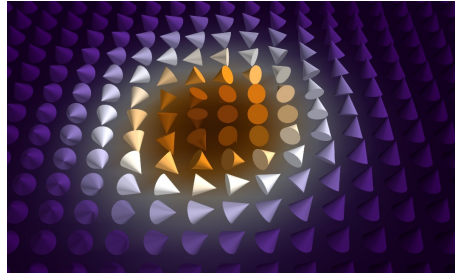
Racetrack Memory (Parkin et al. 2008)

- Compromises
- Magnetic domains represent bits, driven by bursts of spin-polarised current (spin-momentum transfer).
- “3D” structure, for compactness
- Permalloy (it’s a ferromagnet)



Skyrmions

- A vortex-like defect in the magnetic moment field.
- Have position, and interactions with other magnetic structures.
- Phase transitions
- Detected in helimagnets and multilayer ferromagnets.



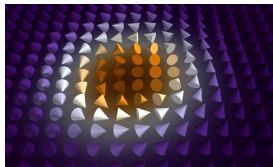
For Racetrack Memory

Skyrmions can:

- be much smaller than domain walls (50nm vs atom spacings).
Better storage density!
- be driven by much weaker spin-polarised currents under light pinning (10^{12}Am^{-2} vs 10^6Am^{-2} (very roughly)). **Less power required to shift!**

The catch?

- Stability (not insurmountable, just unknown).
- Smaller material “parameter space”.



Skymion Logic (Zhang et al. 2015)

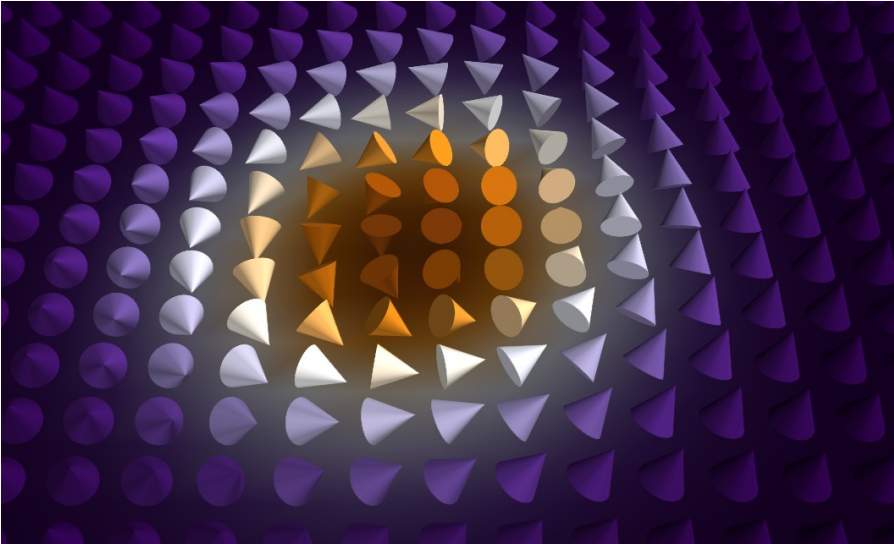
Skymion Logic (Zhang et al. 2015)

- 1ns transfer time.
- All simulated, but a popular research area today.

Micromagnetic Model: The Magnetisation

- The motion of an atom's electron creates a magnetic dipole.
- Sum over all electrons, and intrinsic moments, to get an atom's magnetic moment.
- Model these magnetic moments as vector field $\hat{\mathbf{m}}(\mathbf{x})$ (normalised).
- Continuum assumption





Micromagnetic Model: Exchange Energies

- Isotropic exchange energy favours aligned neighbouring moments:

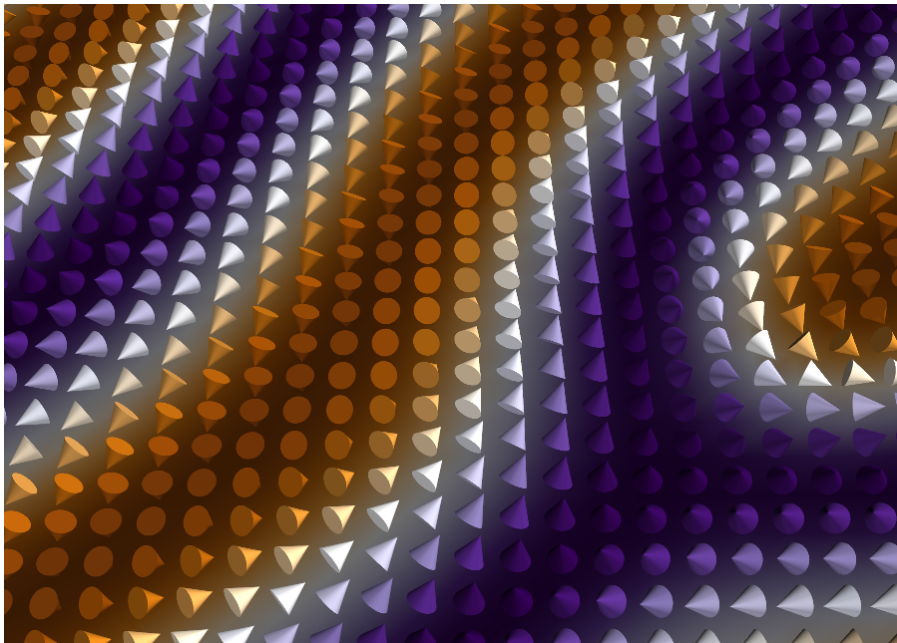
$$w_{\text{exch}}(\hat{\mathbf{m}}) = A (\|\nabla \mathbf{m}_x\|^2 + \|\nabla \mathbf{m}_y\|^2 + \|\nabla \mathbf{m}_z\|^2) .$$

- Dzyaloshinskii-Moriya exchange favours perpendicular neighbouring moments (from helimagnets/multilayers):

$$w_{\text{dmi}}(\hat{\mathbf{m}}) = D \hat{\mathbf{m}} \cdot (\nabla \times \hat{\mathbf{m}}) .$$

- The compromise forms a helix:





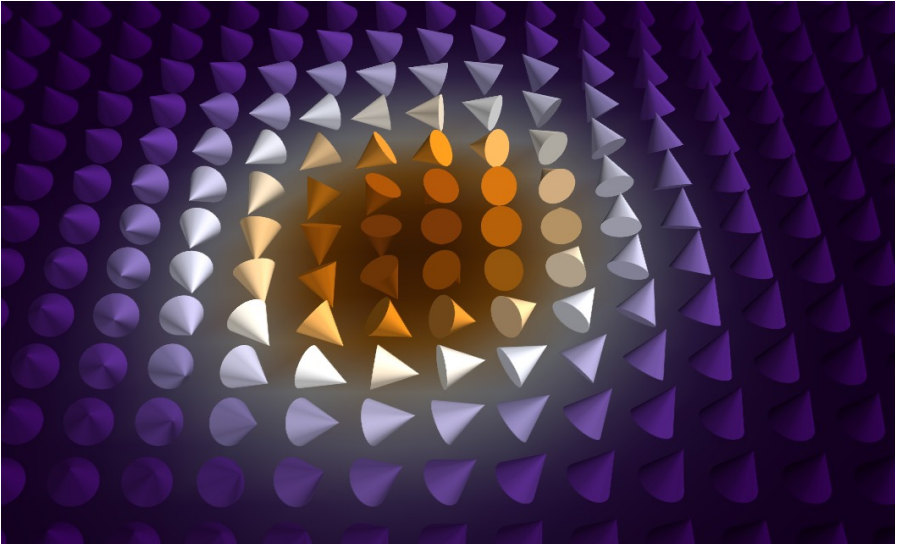
Micromagnetic Model: Zeeman

- What happens when you put a strong magnet next to it...

$$w_{\text{zeeman}}(\hat{\mathbf{m}}) = -\mu_0 M_S \hat{\mathbf{m}} \cdot \mathbf{H}$$



But when everything is just right...



Other Energies

- Various anisotropies:
 - Magnetocrystalline (electron orbital positioning, doping)
 - Magnetostriction (straining)
- Demagnetisation (think bar magnets, long-range)

$$w_{\text{demag}}(\hat{\mathbf{m}}) = -\frac{\mu_0 M_S}{2} (\mathbf{H}_N \cdot \hat{\mathbf{m}}), \quad \mathbf{H}_N = -\nabla U,$$

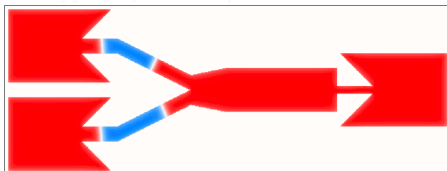
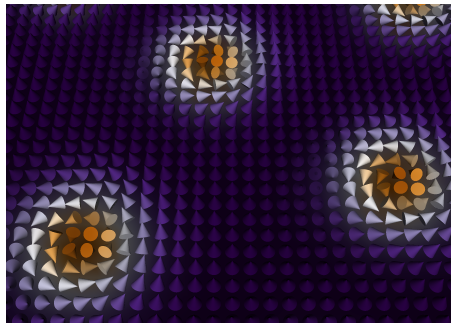
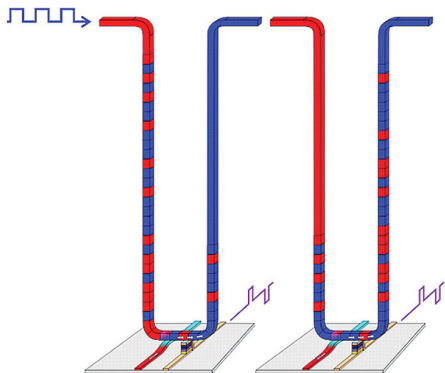
$$U(\mathbf{x}) = \frac{M_S}{4\pi} \left(\int_S \frac{\hat{\mathbf{n}} \cdot \hat{\mathbf{m}}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} dS' - \int_V \frac{\nabla' \cdot \hat{\mathbf{m}}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} dV' \right)$$

Then you need your supercomputer...

Then you need your supercomputer...

- Event-based computing?
- It's an initial value problem

**...but it's a cool research field,
and it might just be useful.**



Energy-Driven Dynamics

- Landau-Lifshitz (1939) -Gilbert (2004) phenomenological dynamics
- Energies combine to create an effective magnetic field:

$$\mathbf{H}_{\text{eff}}(\mathbf{x}_0, t_0) = -\frac{1}{\mu_0 M_S} \frac{\delta W[\hat{\mathbf{m}}(\mathbf{x}, t)]}{\delta \hat{\mathbf{m}}(\mathbf{x}_0, t_0)}$$

- This effective field perturbs the magnetic moment field:

$$\frac{\partial \hat{\mathbf{m}}}{\partial t} = \underbrace{-|\gamma| \hat{\mathbf{m}} \times \mathbf{H}_{\text{eff}}}_{\text{precession}} + \underbrace{\alpha \hat{\mathbf{m}} \times \frac{\partial \hat{\mathbf{m}}}{\partial t}}_{\text{damping}}$$

- It's an initial-value problem!

Challenges

- Material and geometry selection still a bit up in the air, but people are gravitating towards multilayer materials.
- Pinning mechanisms (notches, holes, material boundaries)
- Behaviour is difficult to verify experimentally (equipment and expertise). Everything I've said here has been observed experimentally.
- Many carriers under consideration (spin waves and magnons, domain walls, merons, antiskyrmions).