

Theme 4

Platforms, Architectures and Demonstrators

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PRiME Industry Day

London, 30 June 2015



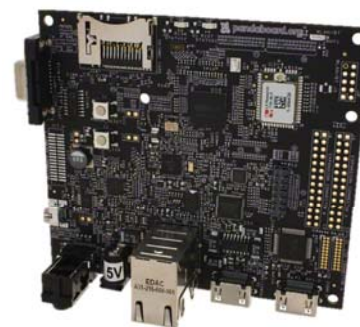
What is Theme 4?

- Platforms and Architectures
 - A range of platforms to support **PRiME**'s research
 - The homogeneous SpiNNaker platform
 - Does a manycore architecture = ($n * \text{multicore}$)?
- Demonstrators (*and Applications*)
 - To showcase **PRiME** research

Platforms & Architectures

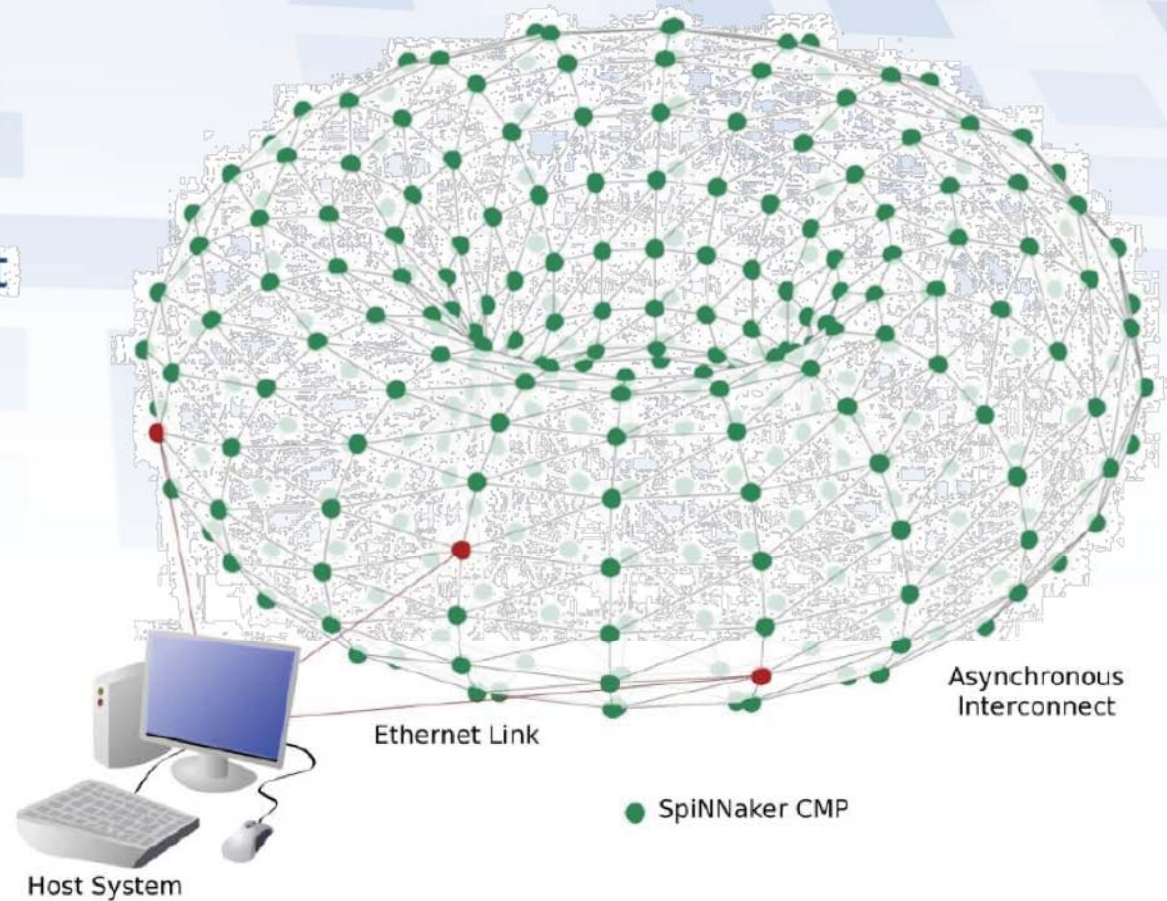
Platforms and Architectures

- Heterogeneous Many-Core Platforms
 - Developed a Linux build for Cyclone V which meets **PRiME**'s OS requirements for the heterogeneous platform.
 - Integrating the heterogeneous platform with Theme 3 instrumentation for slack time measurement.
- Homogeneous Many-Core Platforms
 - Understanding of capability of existing COTS platforms
 - SpiNNaker: Implementing run-time mechanisms

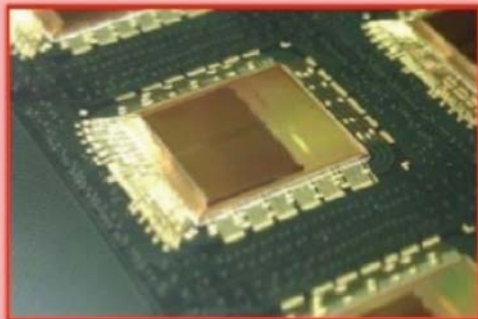


The SpiNNaker project

- A million mobile phone processors in one computer
- Able to model about 1% of the human brain...
- ...or 10 mice!

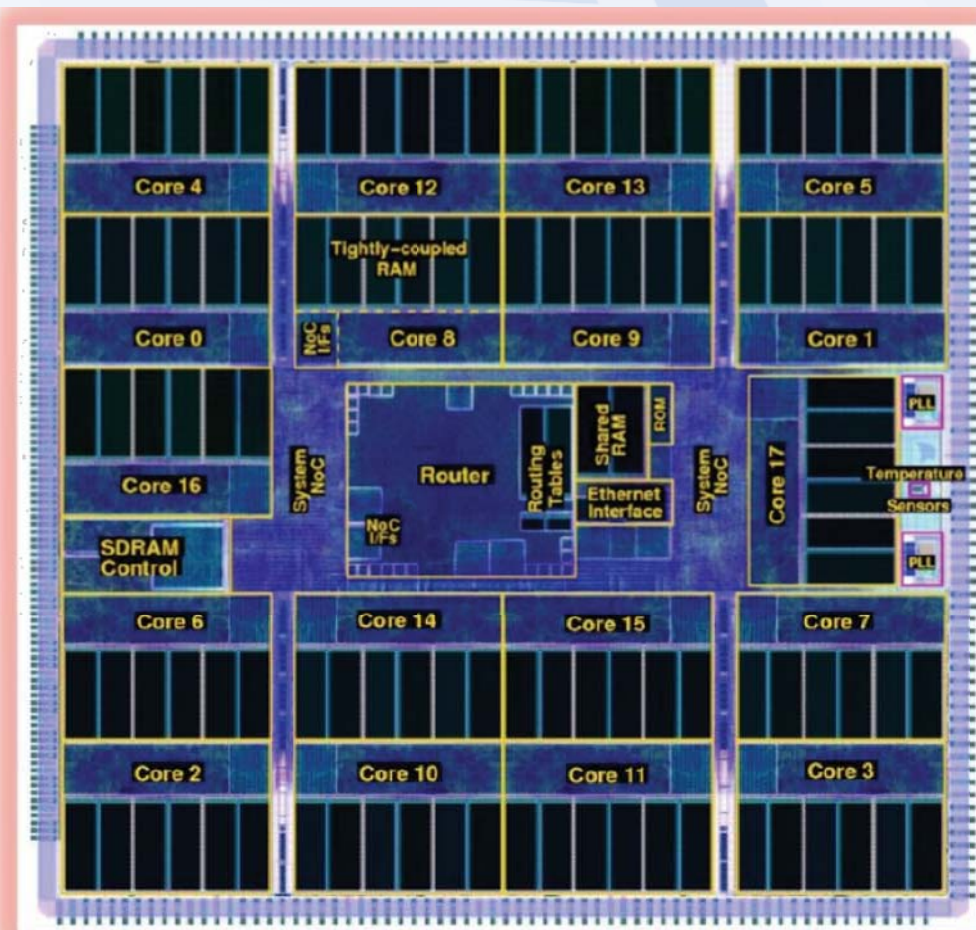


The SpiNNaker project

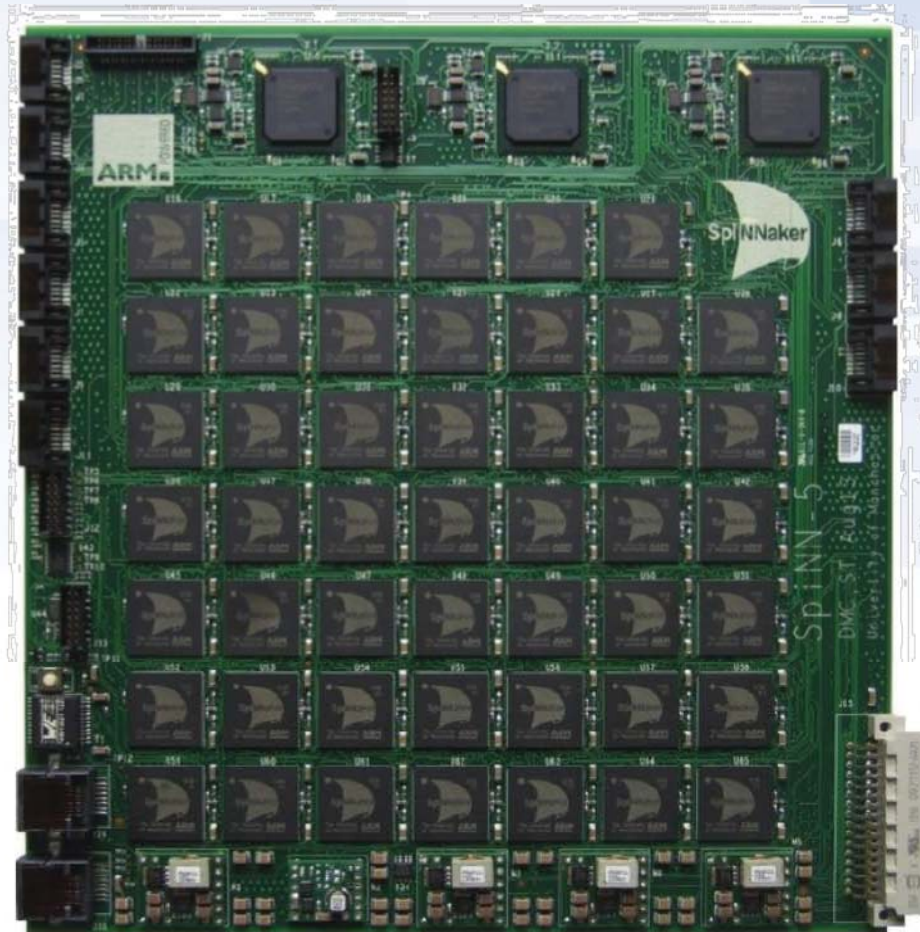


Mobile
DDR
SDRAM
interface

Multi-chip
packaging by
UNISEM Europe



The SpiNNaker project

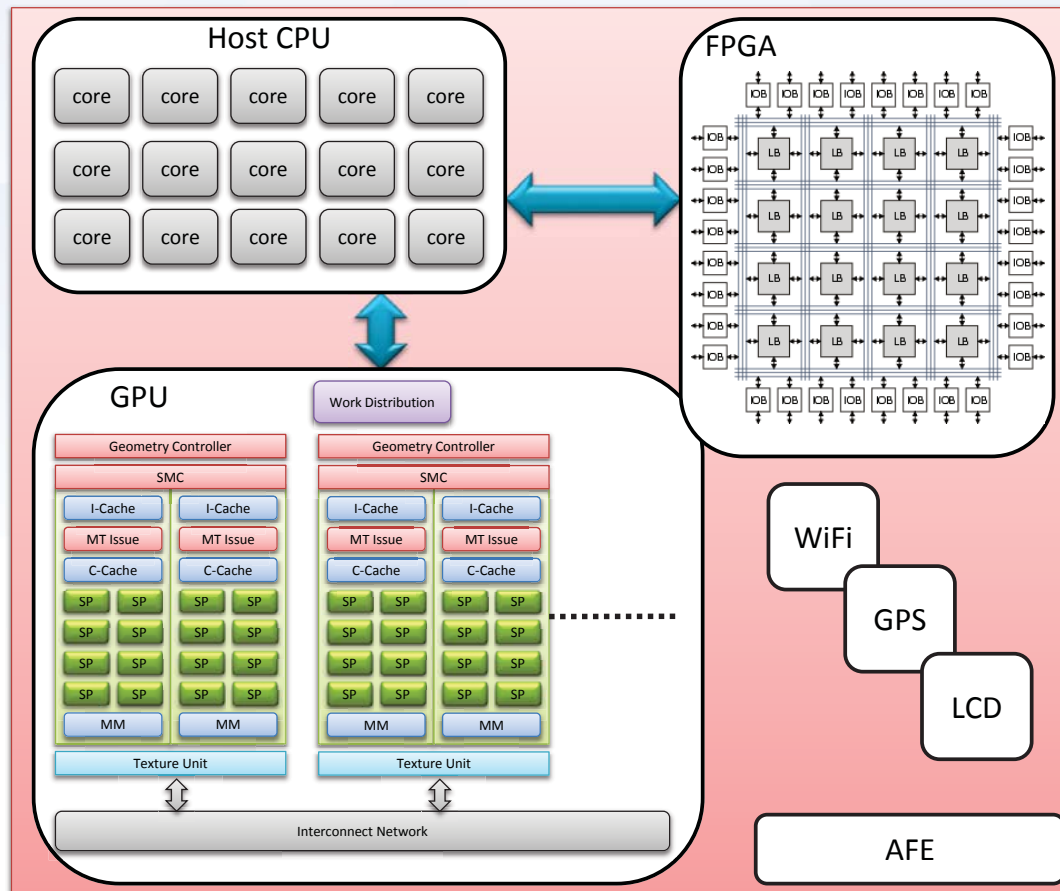


The SpiNNaker project



Can run-time fault recovery and load-balancing be compatible with delivering continuous real-time performance on a system such as SpiNNaker?

Future Many-core Architectures



- Some architectures can 'approximate' this (and may appear as we progress).
- For others, we can use simulation.
 - Gem5
 - VLAB

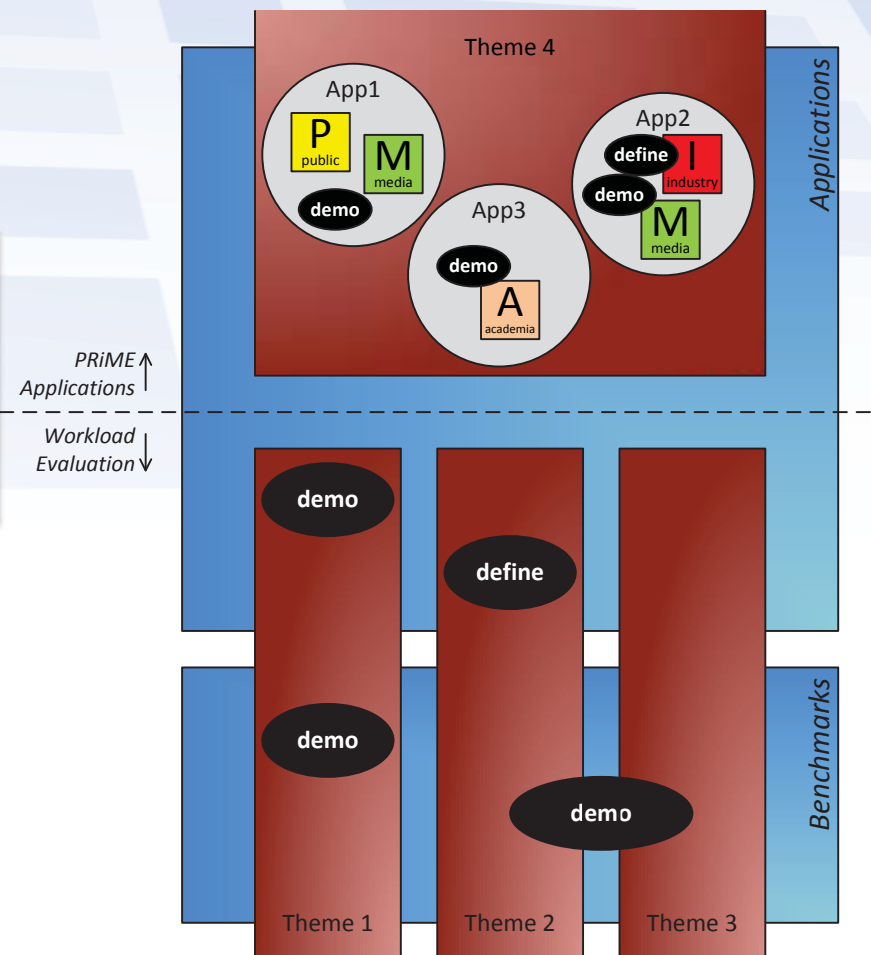
Applications & Demonstrators

Applications & Demonstrators

“ An unfortunate computer science tradition is we build research prototypes, then wonder why applications people don't use them. ”

Asanovic et al., “A view of the parallel computing landscape,” *Commun. ACM*, vol. 52, iss. 10, pp. 56-67, 2009.

- Workloads needed to:
 - Enable individual research efforts to demonstrate benefits/advantages. (*evaluation workloads*)
 - Create engaging *showcase applications*, focussing research on common drivers/goals, and showcasing cross-theme outcomes.
- Workloads used to showcase research (*demonstrate*), or inform research challenges (*define*).
- PRiME is not trying to invent many-core killer applications



Applications in PRiME

- Applications and Demonstrators draft report produced, and workshop held to discuss
- Applications and Demonstrators wiki growing, aiding cross-theme/institution involvement.
- Experimentation with identified benchmarks on existing platforms (ODROID/Xeon Phi etc)
- Cross-theme demonstrator produced



Applications and Workloads

- Underpinning Algorithms:

- Computer vision
- Computer graphics
- Machine learning
- Multimedia
- Data mining

- Application Domains:

- Healthcare
- Transport and Automotive
- Gaming
- Safety and Security
- Networking and Comms
- Robotics
- High Performance Computing
- Consumer Electronics
- IoT, Smart Cities, Smart Buildings

<i>Application Domain</i>	<i>Computer Vision</i>	<i>Computer Graphics</i>	<i>Machine Learning</i>	<i>Multimedia</i>	<i>Data Mining</i>
Healthcare	■		■	■	
Transport and Automotive	■	■	■	■	■
Gaming	■	■	■		
Safety & Security	■		■		■
Networking & Communication				■	
Robotics	■		■		
High Performance Computing			■		■
Consumer Electronics				■	■
IoT, Smart Cities, Building Automation	■		■		

Requirements of an Application

- Scalability: **prIME**
 - Should scale to make use of available computing resources.
 - Highly parallel (existing HPC?) or multiple concurrent applications.
- Power: **Prime**
 - Aligned with a need and capability of reducing power/temperature.
- Reliability: **pRime**
 - Tolerating errors/imprecision (approximate computing)
 - Meeting reliability requirements (critical systems)
- Getting ‘Bang for Buck’
 - Available/open source code, already parallelised
 - Suitable for execution on heterogeneous platforms
- Relevant to stakeholders

Showcase Demonstrator?

Current thinking

Application domain for stakeholder 1

Automotive

Application domain for stakeholder 2

Consumer Electronics

a 'class' of algorithm

(Embedded) Computer Vision Algorithms

Edge
Detection

Face
Recognition

Stereo
Imaging

Image
Alignment

Showcase Demonstrator?

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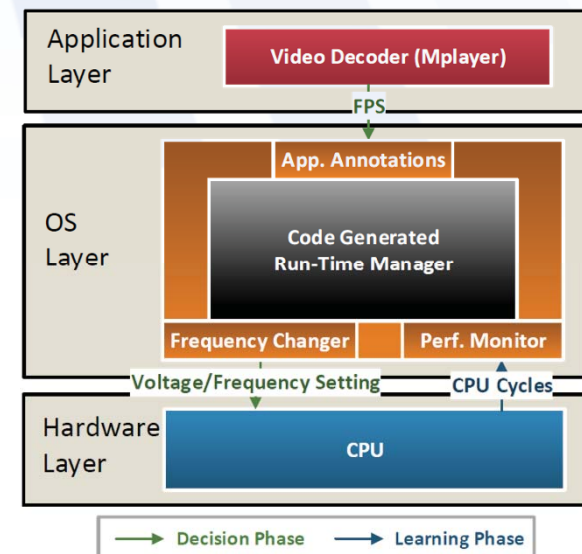
Face
Recognition

Image
Alignment

Today's Demonstrators

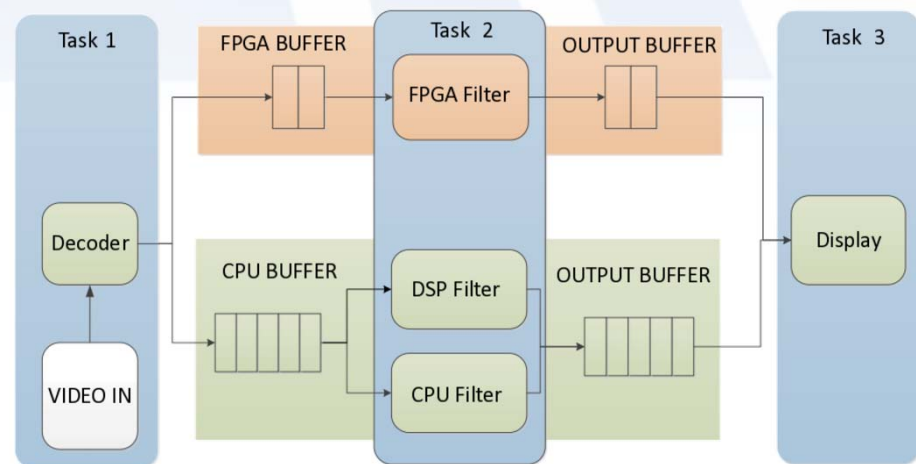
1. Formal methods for design & verification of RTM software & automatic RTM code generation

- Formal methods are mathematical techniques for the specification and development of complex systems which can be used to thoroughly verify the properties of a system, increasing the reliability and robustness of the design. Event-B is a formal method for system-level modelling and analysis which is used to create a formal model of the Run Time Management (RTM) software. This RTM formal model can be automatically translated into executable code to be run on the hardware, reducing the effort of hand-coding the implementation, and is portable across different architectures and Operating Systems.



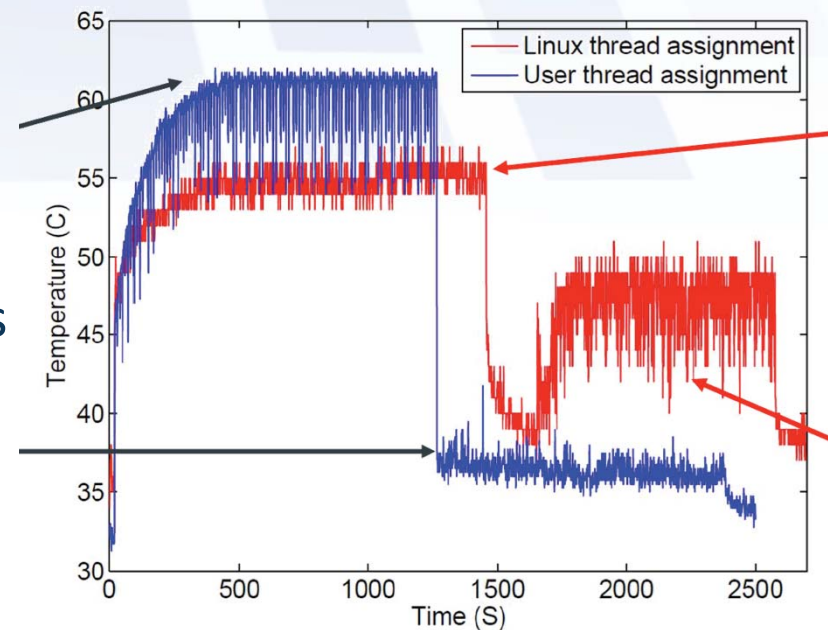
2. Adaptive energy optimisation techniques in heterogeneous embedded systems (CPU, DSP etc)

- PRiME has developed a novel adaptive energy minimization approach for embedded heterogeneous systems. This is based on a runtime model - generated through regression-based learning of energy and performance trade-offs between the different computing resources in the system. Using this model, an application task is mapped to the most suitable computing resource during runtime, to minimize energy consumption for the application's performance requirement. Also used is DVFS control which adapts to the performance and workload variations.



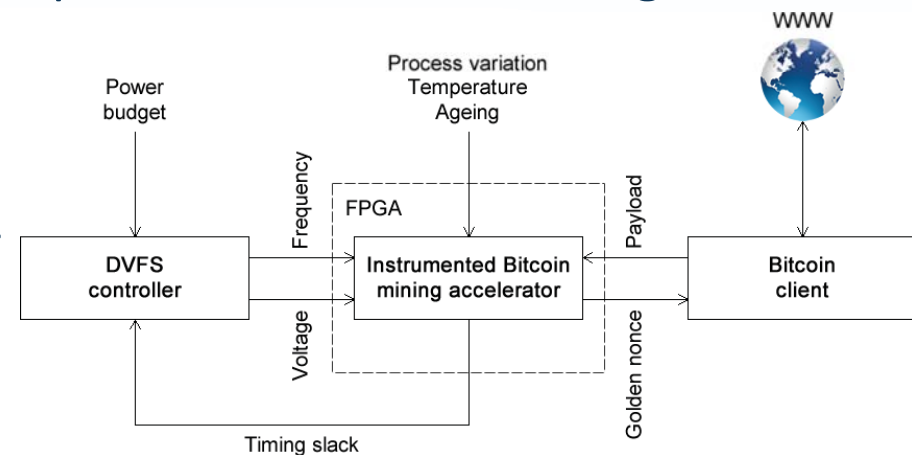
3. Energy-efficient thermal management of embedded systems

- This demonstrates thermal management techniques to improve the lifetime reliability of embedded systems. PRiME has investigated three main thermal parameters – peak temperature, average temperature and thermal cycling. Two control levers are used – CPU voltage-frequency and thread allocation – and the underlying control algorithm for managing energy and temperature is based on reinforcement learning principles, specifically Q-learning. Significant thermal improvements and energy reduction are demonstrated.



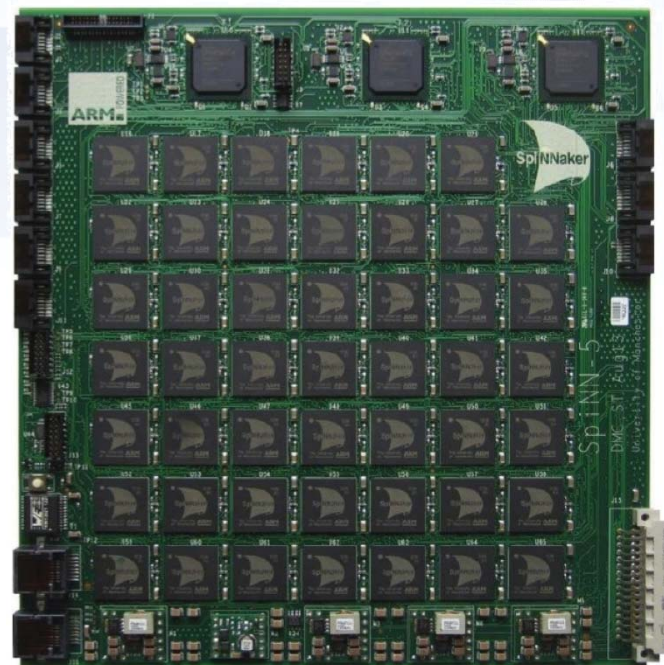
4. DVFS of a custom hardware accelerator using timing slack measurement

- This shows an example of dynamic voltage and frequency scaling (DVFS) of a custom hardware accelerator using timing slack measurement. Slack measurement cells and control logic are added to monitor the most critical timing paths in the design. The combination of timing slack measurement and DVFS allows for the safe erosion of the bulk of timing guardbands introduced by hardware vendors to protect against effects including supply voltage fluctuation, temperature change, process variation and degradation. By obtaining information direct from the application circuit, guardbands are able to be reduced from tens/hundreds of ns typically seen down to just a few hundred picoseconds.



5. SpiNNaker real-time power measurement and optimisation

- SpiNNaker is a novel, massively parallel computer architecture inspired by the working of the human brain. Each SpiNNaker chip contains 18 ARM968 processors, with 48 chips on each SpiNNaker board. A microcortical neural simulation (small building block of the brain) will be shown running on 15 out of 48 SpiNNaker chips, while measuring the power consumption in real-time of the various parts of the system (SpiNNaker, SDRAM, Peripherals, FPGA, Total power). This will demonstrate the effects of gradually reducing the frequency of the unused chips on the SpiNNaker board while the simulation is running.





Thank you!

Any Questions?

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